

Physics Applications in the ALEGRA Framework

1st MIT Conference on Fluid and Solid Mechanics

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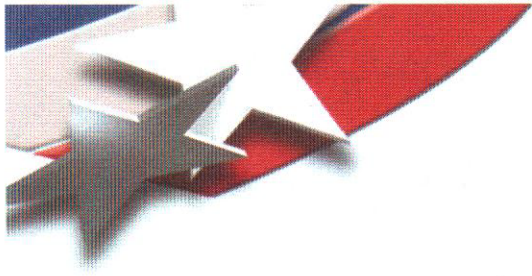
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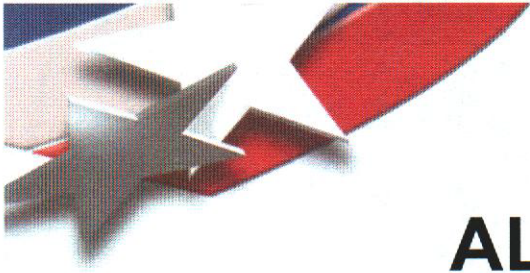
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Overview

- **ALEGRA Physics Framework**
- **Solid Dynamics and General Capabilities**
 - Lagrangian-ALE-Eulerian
 - Materials
- **Advanced Physics**
 - Transient Electromagnetics
 - Electromechanics
 - Electro-quasistatic mechanics
 - Magnetohydrodynamics

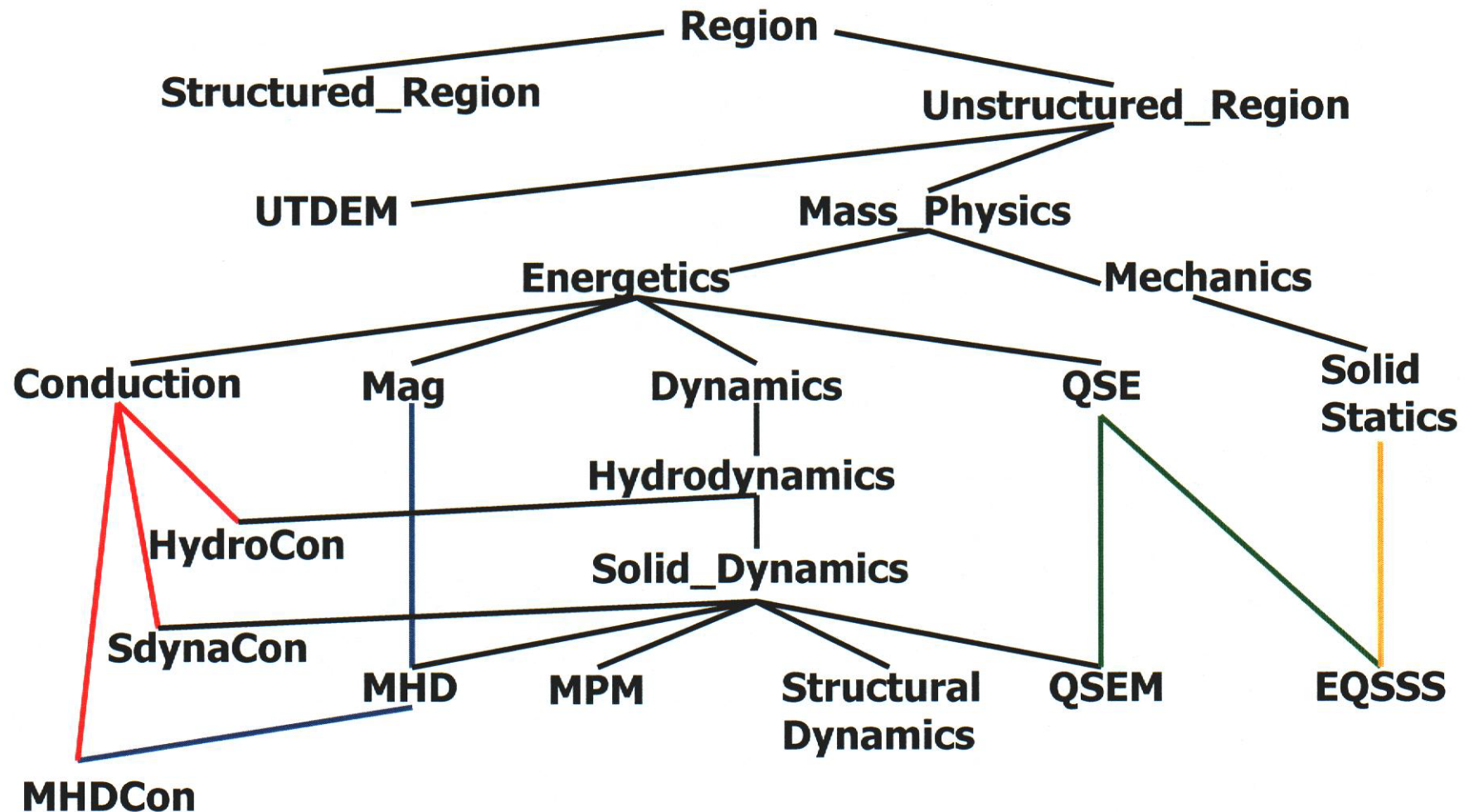


ALEGRA Physics Framework

- **ALEGRA supports a variety of physics classes**
 - **Basic, single physics solutions – examples:**
 - Solid dynamics
 - Magnetism
 - Electrostatics
 - **Coupled physics solutions - examples**
 - Electromechanics
 - Magnetohydrodynamics
 - Transient electromagnetics
 - **Each physics is derived from a basic, abstract physics class, containing the discretization topology.**



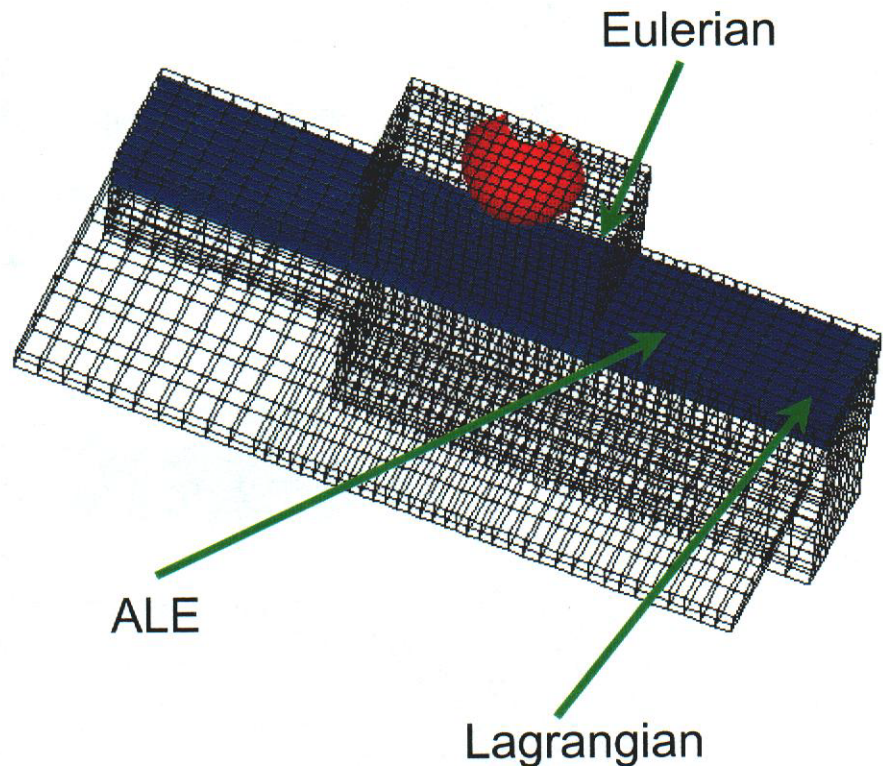
ALEGRA Physics Hierarchy (abridged)

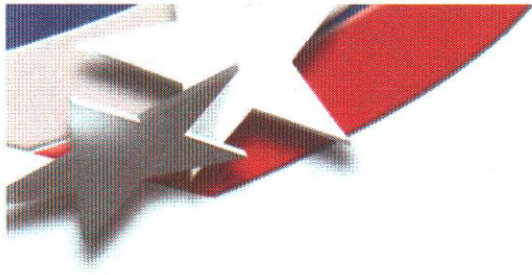




Multi-Material ALE and Solid Dynamics

- Region composed of Element Blocks
- Element Blocks may be Lagrangian, ALE, or Eulerian
- A Region may be composed of many blocks of any mesh type.
- The mesh type of blocks may be changed during calculation.
- ALE and Eulerian blocks must account for advection of material through the mesh
 - ALE mesh smoothing algorithms (Tipton)
 - 2nd order van Leer advection



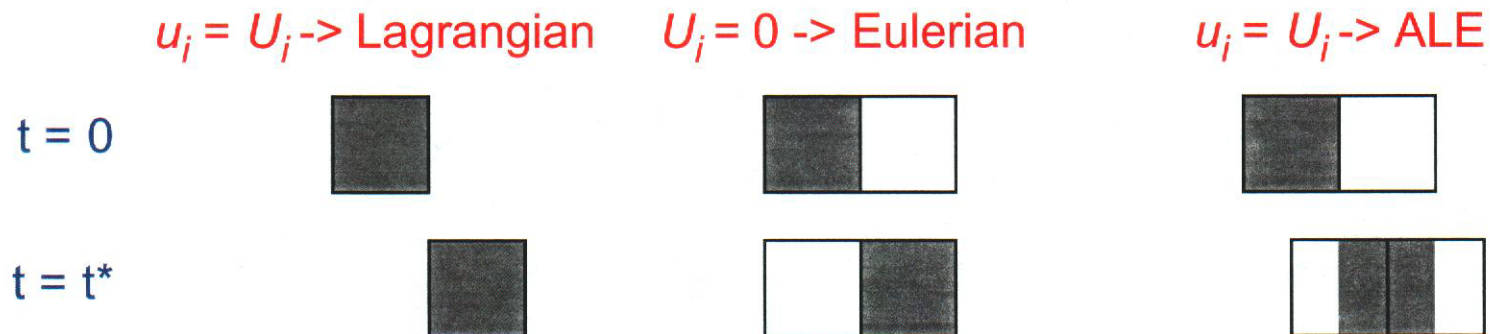


ALE Concept

Integral Form of the Conservation of Mass Equation

$$\frac{d}{dt} \int_V (\rho dV) + \int_s \rho (u_i - U_i) n_i ds = 0$$

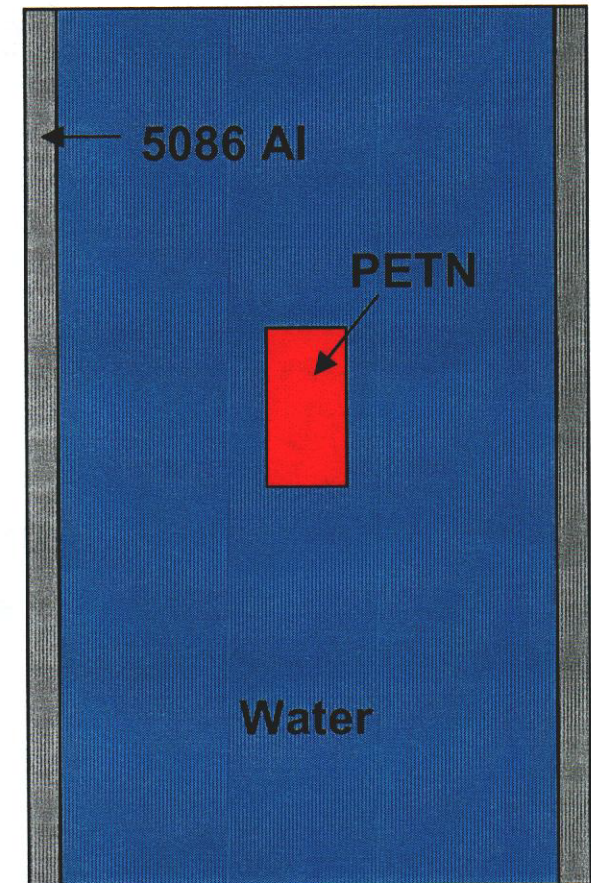
where u_i is the velocity of the fluid and U_i is the velocity of the boundary surface of the grid.





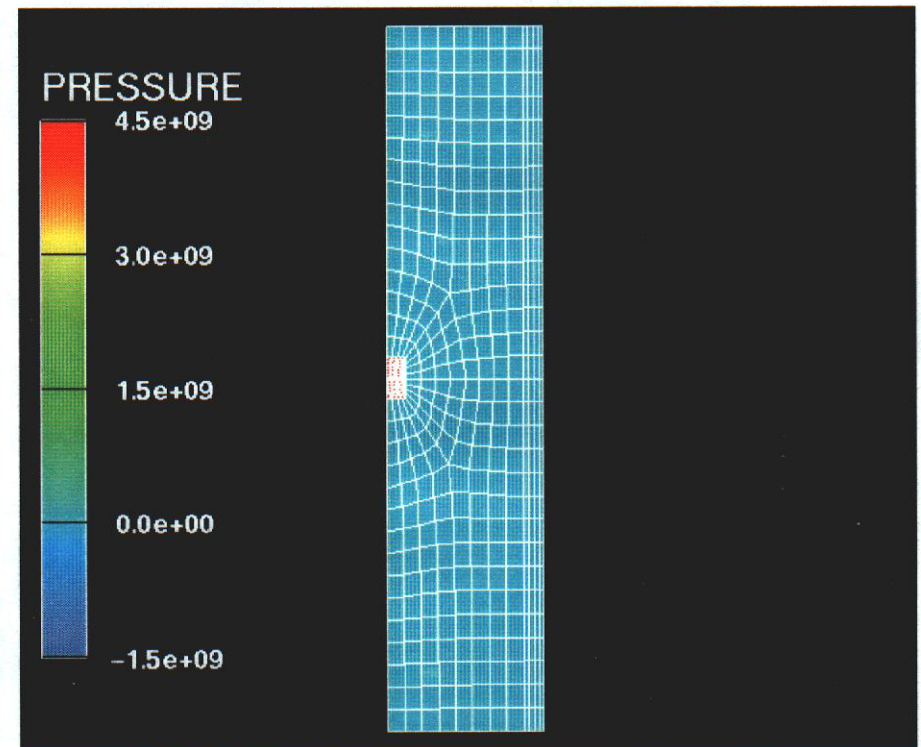
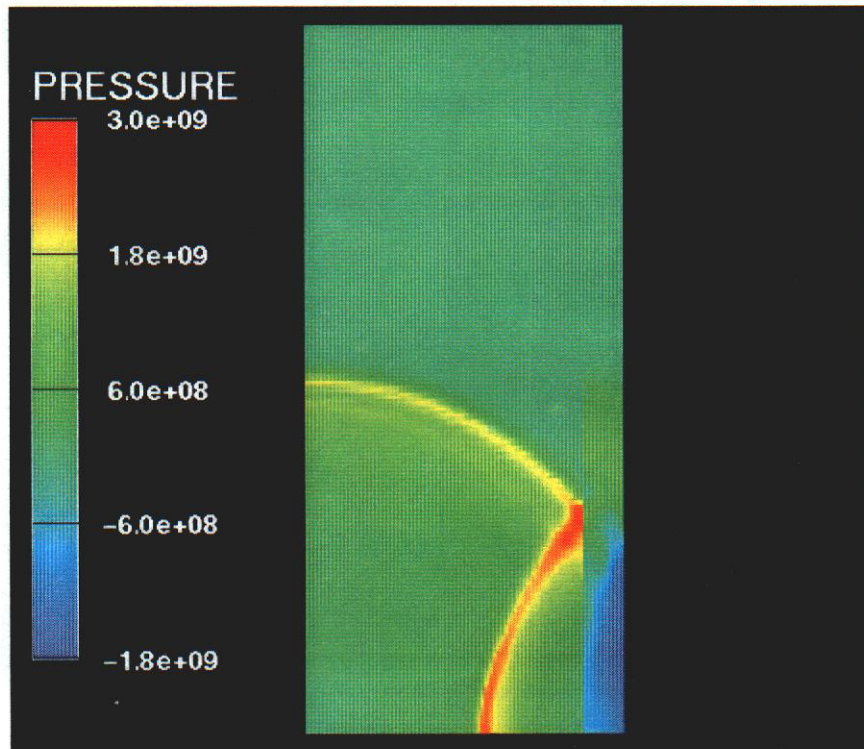
Solid Dynamics: Hydrobulge Simulations

- 9" cylinder, 4" diameter, filled with water and 3-5.7g PETN explosive in center.
- Compare radial velocity and displacement.
- Demonstrate use of several methods for performing calculation:
 - Lagrangian->ALE->Eulerian for explosive and water
 - Lagrangian for cylinder
 - Initial refinement
 - H-Adaptive
 - Parallel





Solid Dynamics: Hydrobulge Simulations

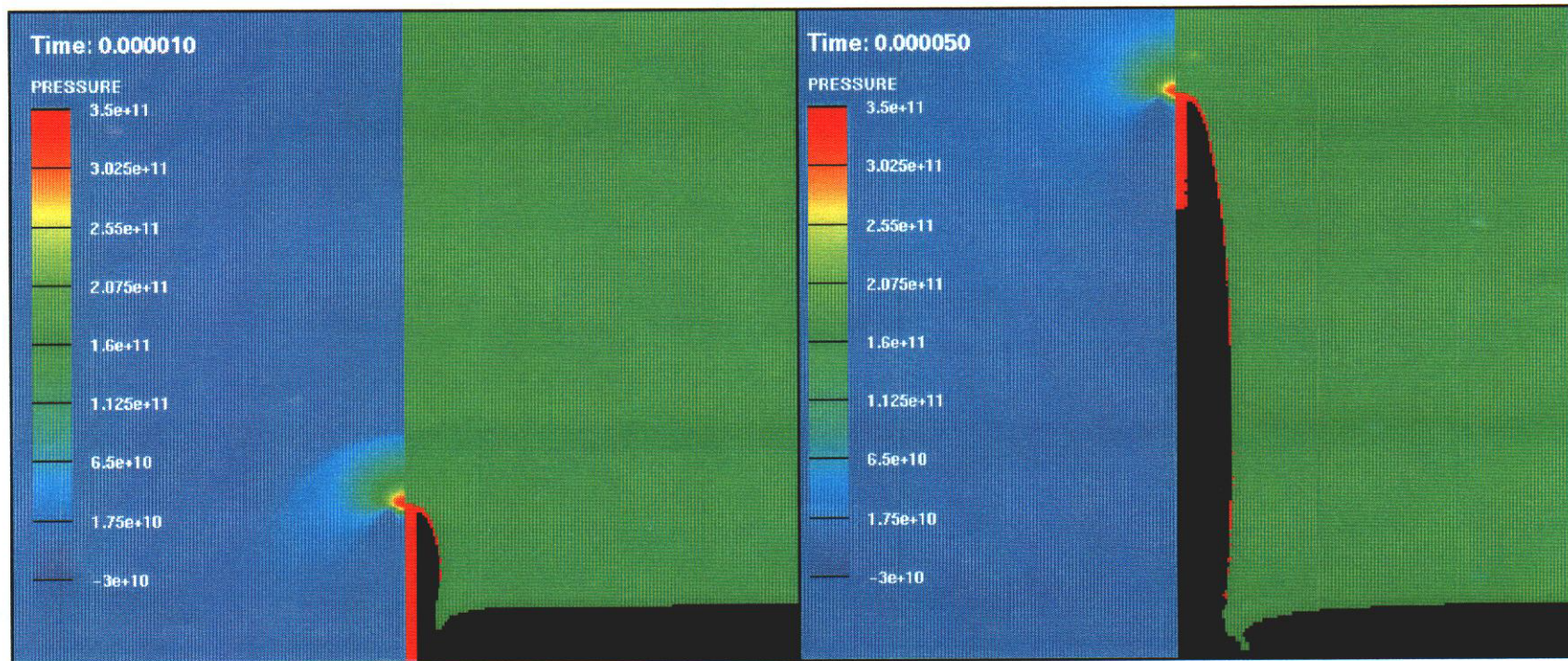


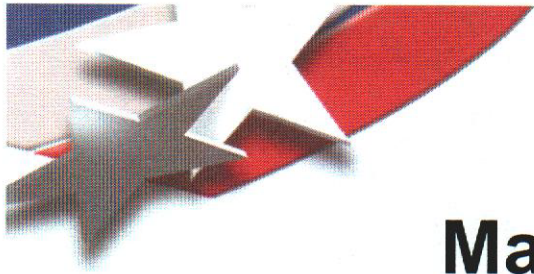
Pressure magnitude (left); with mesh overlay (right)



Solid Dynamics: Long Rod Simulations

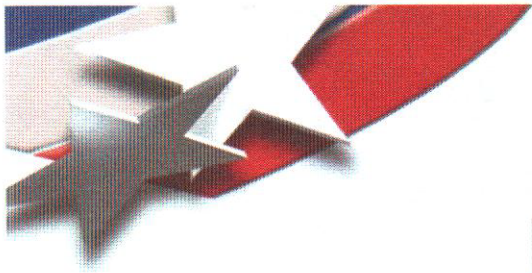
- 2D Cylindrical simulations of long tungsten rods impacting thick RHA plates
 - Impact velocities: 1 – 4.5 km/s
 - Rod Length/Mass: 12 cm / 50 gm, 15 cm / 100 gm





Materials and Material Models

- Material simply defined as a collection of material models.
- Material model is an object that operates on material data.
- Elements may contain zero to all materials at any time.
- Several material models may operate in series to determine the state of the material.
- Material model may be a collection of other material models
- Provide all necessary classes of models
 - Equation of state
 - Constitutive/Yield
 - Fracture
 - HE Burn
 - Conductivity
 - Permittivity
 - and more
- Some models common with CTH and PRONTO
- Material model interface designed for modular rapid model implementation.



Example Material Models

- **EOS:** Mie Gruniesen, Programmed and Reactive Burn models, SESAME
- **Constitutive:** Linear Elastic
- **Yield:** Von Mises, Johnson-Cook, Zerilli-Armstrong, Steinberg-Guinan-Lund, Sandia Visco-plastic
- **Fracture:** Pressure-based void insertion
- **Conductivity:** Lee-More
- **Structural:** Elastic-Plastic for shells



Transient Electromagnetics

Transient Electromagnetics (TEM) in ALEGRA incorporates:

- Two formulations of full-field, unstructured FETD solver with 1st order ABC (operational)**
- Structured FDTD / Hybrid FETD/FDTD solver with PML (implementation in progress)**
- Sub-cell algorithms for wires, slots (operational), material layers and SPICE interface (future)**
- Fully coupled kinetic plasma (particles) (future)**



TEM: Unconditionally Stable Helmholtz Formulation

Edge Elements
(zeroth order):

$$\mathbf{w}_i^{(1)}(r) = w_{i_{n1}} \nabla w_{i_{n2}} - w_{i_{n2}} \nabla w_{i_{n1}}$$

Weak-Form of Maxwell System for Electric Field:

$$\mathbf{T}_e \frac{\partial^2}{\partial t^2} \mathbf{e}_s + \mathbf{B}_e \frac{\partial}{\partial t} \mathbf{e}_s + \mathbf{S}_e \mathbf{e}_s = -\mathbf{D}_e \frac{\partial}{\partial t} \mathbf{I}_w$$

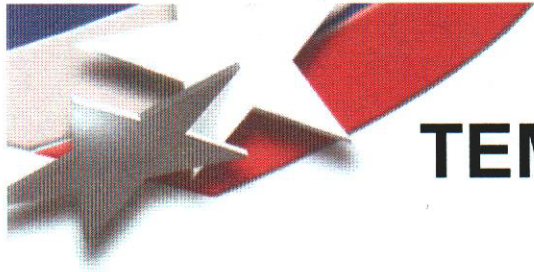
with

Current
Source

$$\mathbf{T}_e = \epsilon_o \int dV \epsilon_r \mathbf{w}_i^{(1)} \cdot \mathbf{w}_j^{(1)} \quad \text{(mass matrix)}$$

$$\mathbf{S}_e = \frac{1}{\mu_o} \int dV \frac{1}{\mu_r} \nabla \times \mathbf{w}_i^{(1)} \cdot \nabla \times \mathbf{w}_j^{(1)}$$

$$\mathbf{B}_e = \int dS \alpha \mathbf{n} \times \mathbf{w}_i^{(1)} \cdot \mathbf{n} \times \mathbf{w}_j^{(1)} + \int dV \sigma \mathbf{w}_i^{(1)} \cdot \mathbf{w}_j^{(1)}$$



TEM: Conditionally Stable Curl-Curl Formulation

Edge and Facet Elements (zeroth order):

$$\mathbf{w}_i^{(1)}(r) = w_{i_{n1}} \nabla w_{i_{n2}} - w_{i_{n2}} \nabla w_{i_{n1}}$$

$$\mathbf{w}_i^{(2)}(r) = 2 \left(w_{i_{n1}} \nabla w_{i_{n2}} \times \nabla w_{i_{n3}} + w_{i_{n2}} \nabla w_{i_{n3}} \times \nabla w_{i_{n1}} + w_{i_{n3}} \nabla w_{i_{n1}} \times \nabla w_{i_{n2}} \right)$$

Strong and Weak form Maxwell System for Magnetic and Electric Fields (respectively):

$$\frac{\partial}{\partial t} \mathbf{b}_A = -\mathbf{C} \mathbf{e}_s - \mathbf{D}_m \mathbf{V}_s \quad \leftarrow \text{Standard FDTD form (but on arbitrary grid)}$$

$$\mathbf{T}_e \frac{\partial}{\partial t} \mathbf{e}_s = \mathbf{C}^t \mathbf{T}_f \mathbf{b}_A - \mathbf{D}_e \mathbf{I}_w \quad \text{with}$$

$$\mathbf{T}_e = \epsilon_o \int dV \epsilon_r \mathbf{w}_i^{(1)} \cdot \mathbf{w}_j^{(1)}$$

$$\mathbf{T}_f = \frac{1}{\mu_o} \int dV \frac{1}{\mu_r} \mathbf{w}_i^{(2)} \cdot \mathbf{w}_j^{(2)}$$



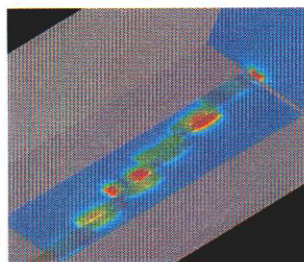
TEM: Implementation

- **The TEM unstructured FETD solver inherits from Unstructured_Region**
- **The TEM structured FDTD solver inherits from Structured_Region**
- **Coupling between these regions for Hybrid EM involves a controller class**
- **Coupling between EM and Radiation will occur via multiple inheritance**
- **TEM utilizes the Aztec CG solver and Nemesis mesh decomposition**



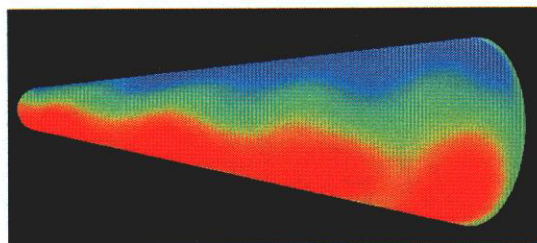
TEM: Application Areas at SNL

Electrical Packaging



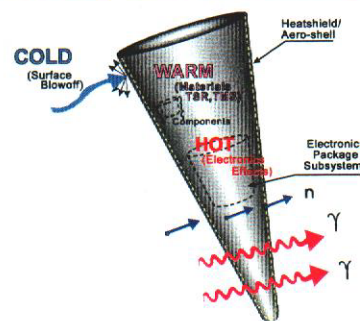
*Multiple Components,
Coupled EM &
Non-Linear Circuits*

EMR / EMC / EMI



*Electrically Large, Geometric
Detail, High Dynamic Range*

Hostile Environments



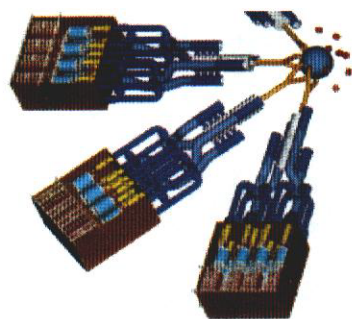
*Coupled Physics,
Complex Geometry*

Lightning Safety



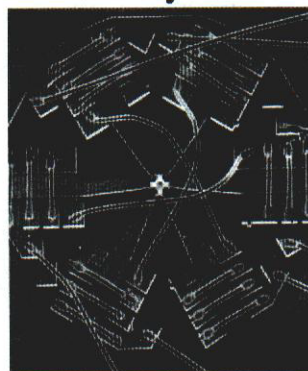
*Wide Frequency Range,
Complex Geometry*

Beams: Radiography / Neutron Generator Tubes



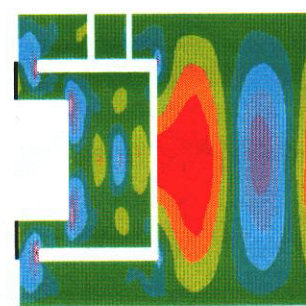
*Coupled Physics,
Complex Geometry*

Microsystems



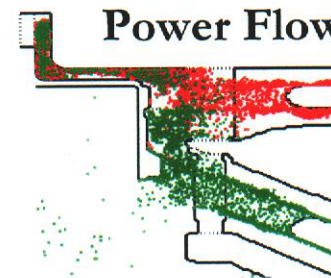
*High Accuracy,
Complex*

Antennas / High- Power Microwaves

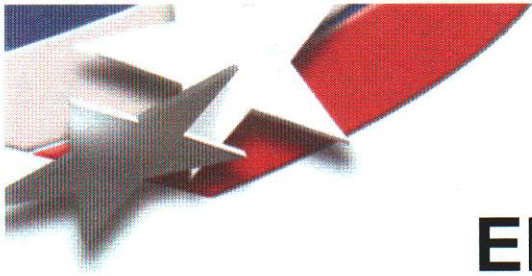


Large and Complex

Z-pinch Power Flow



*High Magnetic Fields,
Multiple Plasma
Density Scales*



Electromechanics Overview

- Electromechanics modeling is generally interested in time scales much larger than speed of light time scales. Maxwell equations and coupling terms can be simplified.

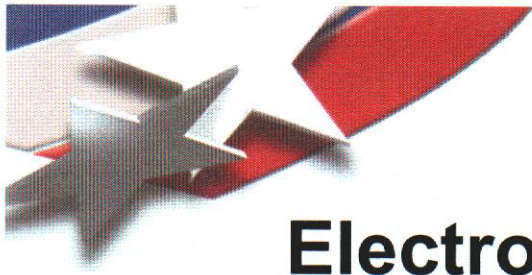
$$\frac{l}{c} = \frac{0.01m}{3.0 \times 10^8 m/s} = 33 ps = \tau_{em} \gg \tau_{mechanics}$$

$$\tau_m = \mu_0 \sigma_0 l^2$$

$$\tau_e = \epsilon_0 / \sigma_0$$

$\tau_m < \tau_{em} < \tau_e$ leads to electro-quasistatic mechanics

$\tau_e < \tau_{em} < \tau_m$ leads to magnetohydrodynamics



Electro-quasistatic mechanics (QSEM)

- **First major coupled physics model in ALEGRA.**
- **3D perfect dielectric modeling. Coupling to external circuits through constant potential boundary conditions (perfect conductors).**
- **Modeling devices containing ferroelectric and piezoelectric materials.**
 - Piezoelectric materials produce electrical response due stress and vice-versa.
 - Ferroelectric materials exhibit piezoelectric response and a spontaneous electric polarization. Polarization and permittivity affected by the history of applied electric fields and stresses.



QSEM: Governing Equations

$$\dot{\rho} + \rho \nabla \cdot \mathbf{u} = 0$$

$$\rho \dot{\mathbf{u}} = \nabla \cdot \mathbf{T}$$

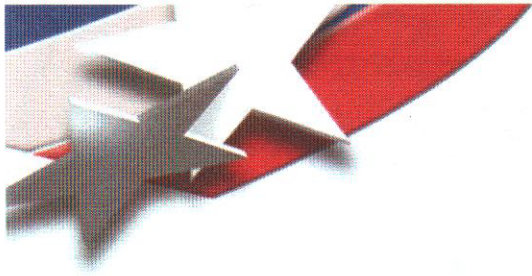
$$\rho \dot{e} = \mathbf{T} : \nabla \mathbf{u}$$

$$\nabla \cdot \mathbf{D} = 0$$

- Constitutive equations close the system.
- Example

$$\mathbf{T} = c\mathbf{S} - \hat{e}\mathbf{E}$$

$$\mathbf{D} = \hat{e}\mathbf{S} + \varepsilon\mathbf{E}$$

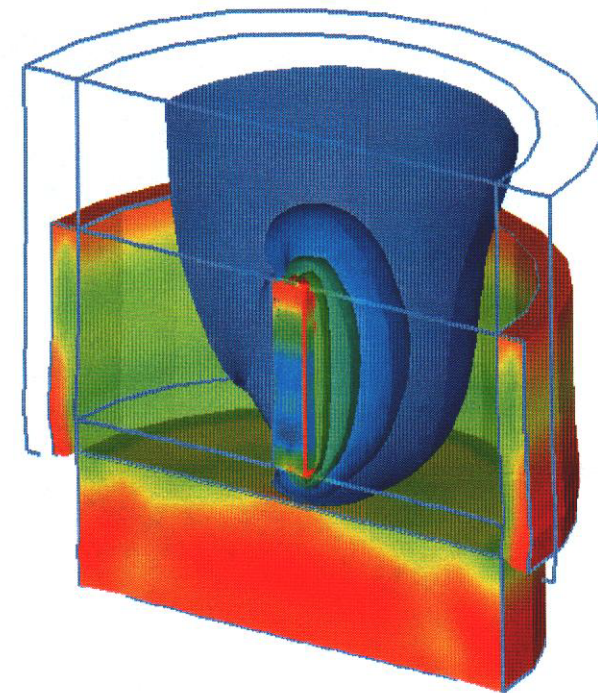
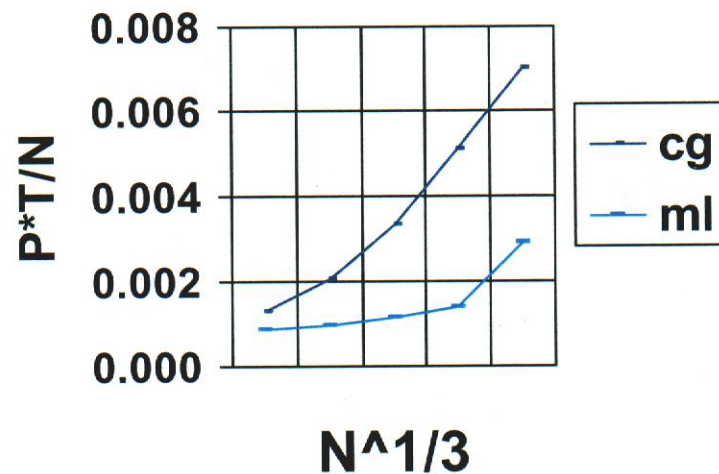
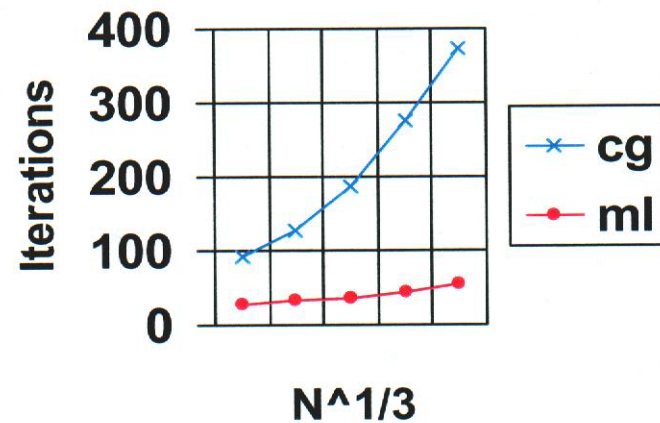


QSEM: Implementation

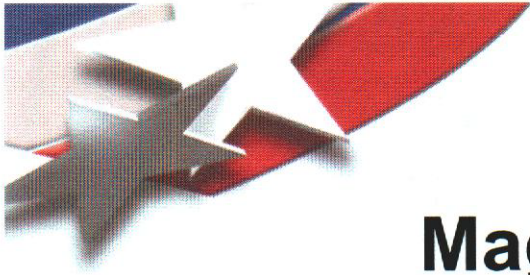
- **Electroquasistatic mechanics** $\nabla \cdot (\epsilon \nabla \phi) = \nabla \cdot \mathbf{p}$
 - Electroquasistatics is implemented as a separate physics class (Qse).
 - Solid dynamics is coupled with Qse through multiple inheritance and operator splitting.
 - 1 irregular hex adaptive mesh supported.
- **AZTEC/ML**
 - The Aztec/ML library solves FE matrix for electric potential.
 - Geometric multigrid using ALEGRA initial refinement capability as well as algebraic multigrid (AMG) is available.
- **DASPK** - DAE solver used to couple to external circuits.



QSEM: Simulation of Ferroelectric Ceramic

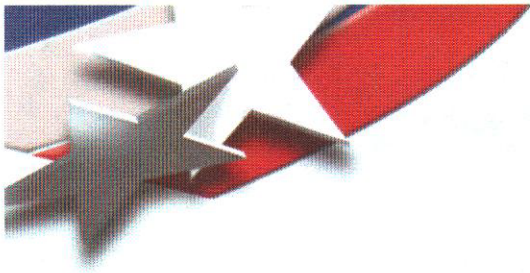


Fused silica flyer plate impacting a bar of poled ceramic. Stress and electric potential isosurfaces shown.



Magnetohydrodynamics (MHD)

- Magnetohydrodynamics models the motion of a fluid continuum in an electrically conducting media.
- 2D
 - B_z out of plane and J_x, J_y in the plane.
 - B_{θ} out of the plane J_r, J_z in the plane.
 - J_z out of the plane with B_x, B_y in the plane (Uses vector potential A_z).
- 3D
- Lagrangian/Remesh/Remap steps supported



MHD: Equations

$$\dot{\rho} + \rho \nabla \cdot \mathbf{u} = 0$$

$$\rho \dot{\mathbf{u}} = \nabla \cdot \mathbf{T} + \mathbf{J} \times \mathbf{B}$$

$$\rho \dot{e} = \mathbf{T} : \nabla \mathbf{u} + \mathbf{J} \cdot \hat{\mathbf{E}}$$

$$\frac{\partial \mathbf{B}}{\partial t} + \nabla \times (\mathbf{B} \times \mathbf{v} + \hat{\mathbf{E}}) = 0$$

$$\nabla \cdot \mathbf{B} = 0$$

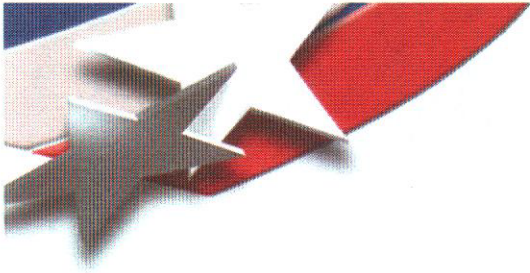
$$\nabla \times (\mathbf{B} / \mu_0) = \mathbf{J}$$

- Constitutive equations close the system.

$$\mathbf{J} = \sigma(\rho, \theta) \hat{\mathbf{E}}$$

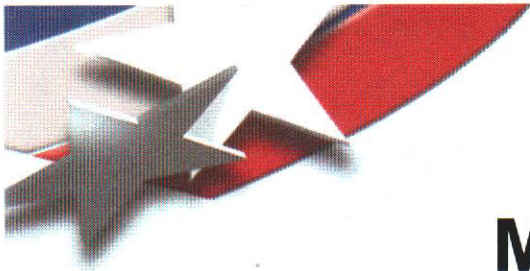
$$\mathbf{T} = -p(\rho, e) \mathbf{I}$$

- Thermal transport and a simple emission radiation model are also available to diffuse and remove energy.

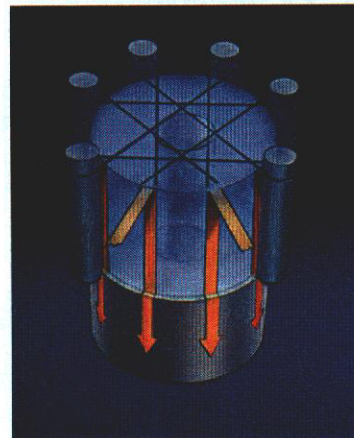
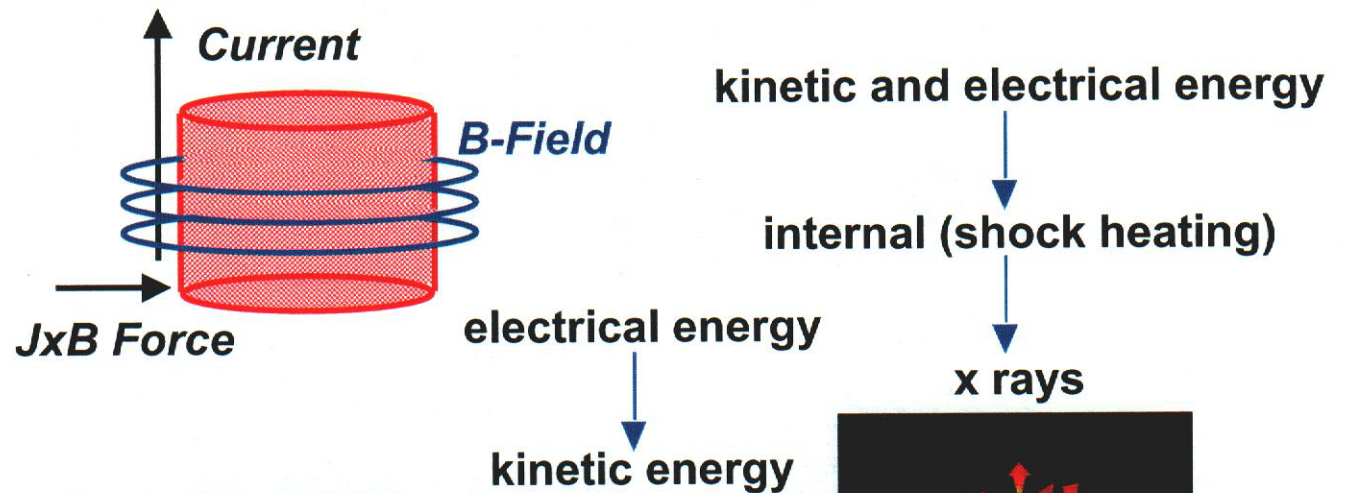
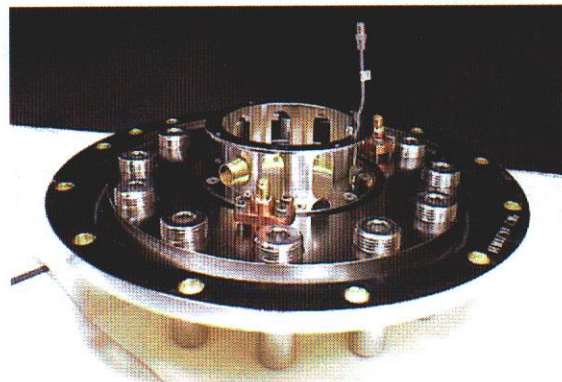
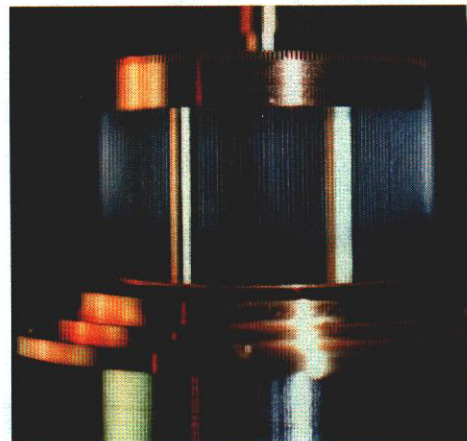


MHD: Implementation

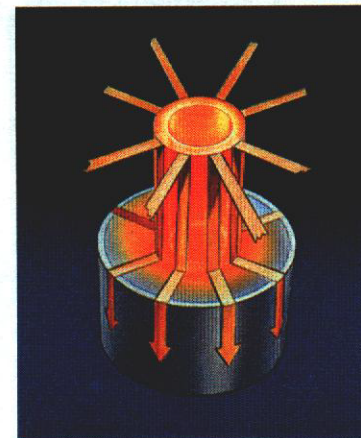
- **Transients magnetics**
 - Transient magnetics is implemented as a separate physics class (Mag).
 - Solid dynamics is coupled with magnetics through multiple inheritance and operator splitting.
- **AZTEC/ML**
 - The Aztec library is used to solve the FE matrices.
 - A new 3D edge/face element based method currently in development requires special AMG.
 - Constrained transport magnetic flux remap strategies are under development.
- **DASPK** - Mesh response coupled to external circuit using DAE solver.



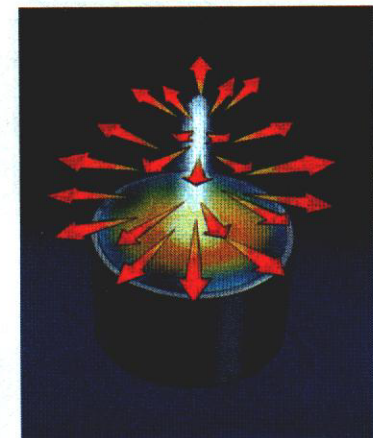
MHD: Z-pinch Applications



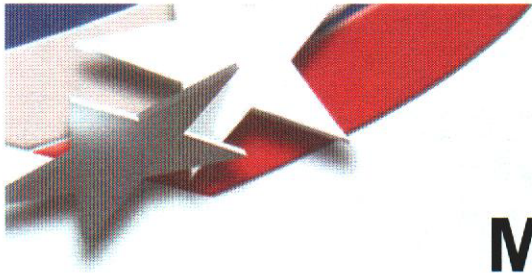
Initiation



Implosion



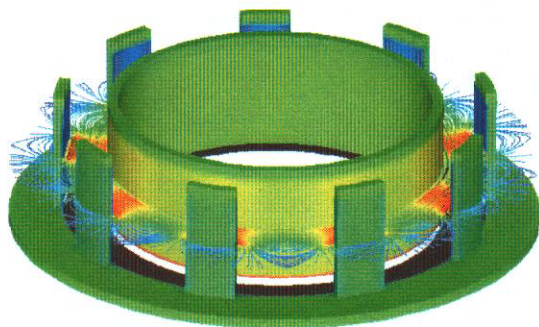
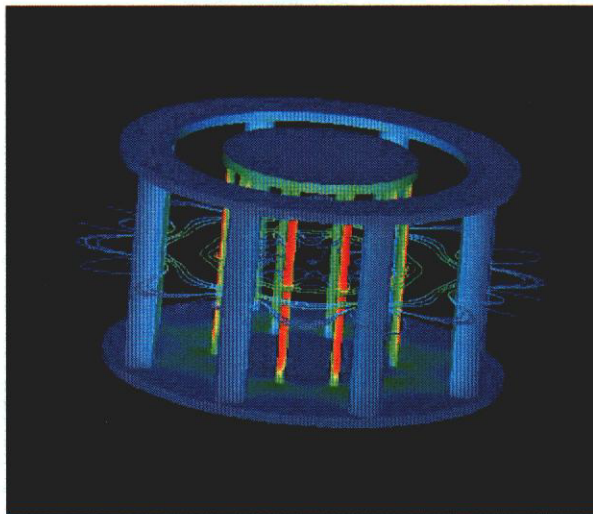
Stagnation



MHD: Example Simulations

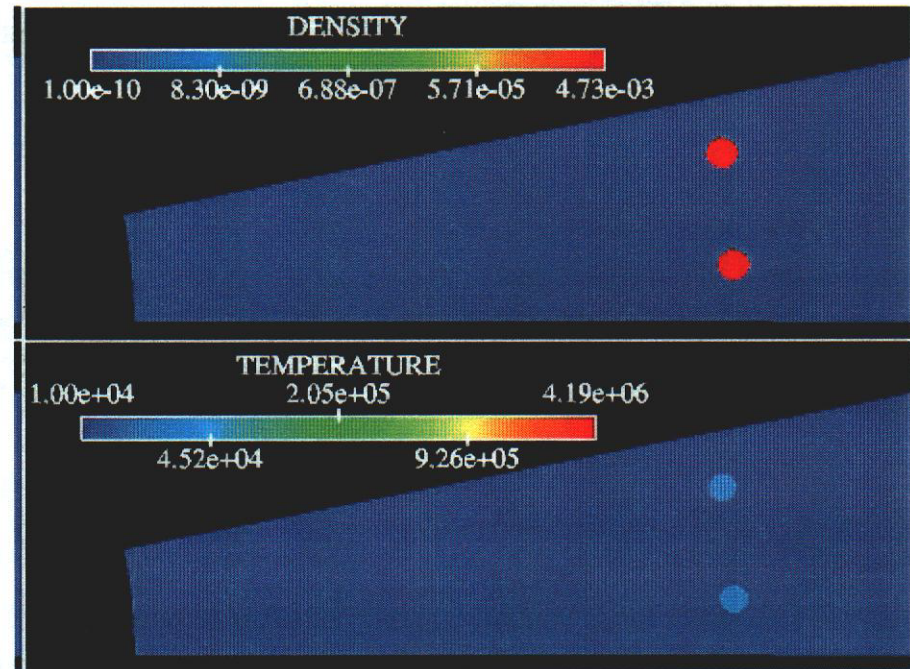
Transient magnetics

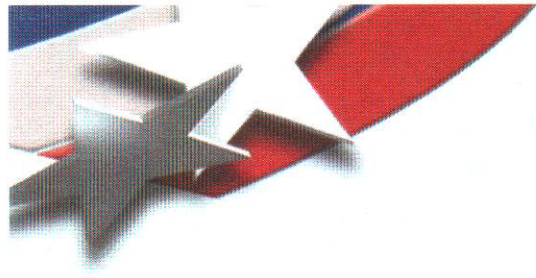
movie



Constrained transport

movie





Conclusion

- **ALEGRA has developed into a framework capable of integrating advanced, coupled physics using a variety of solution methods**
- **Examples of classes of physics solutions:**
 - Solid Dynamics
 - Transient Electromagnetics
 - Electro-quasistatic mechanics
 - Magnetohydrodynamics
- **Methods**
 - Lagrangian, ALE, Eulerian, H-Adaptivity
 - Structured and Unstructured Meshes